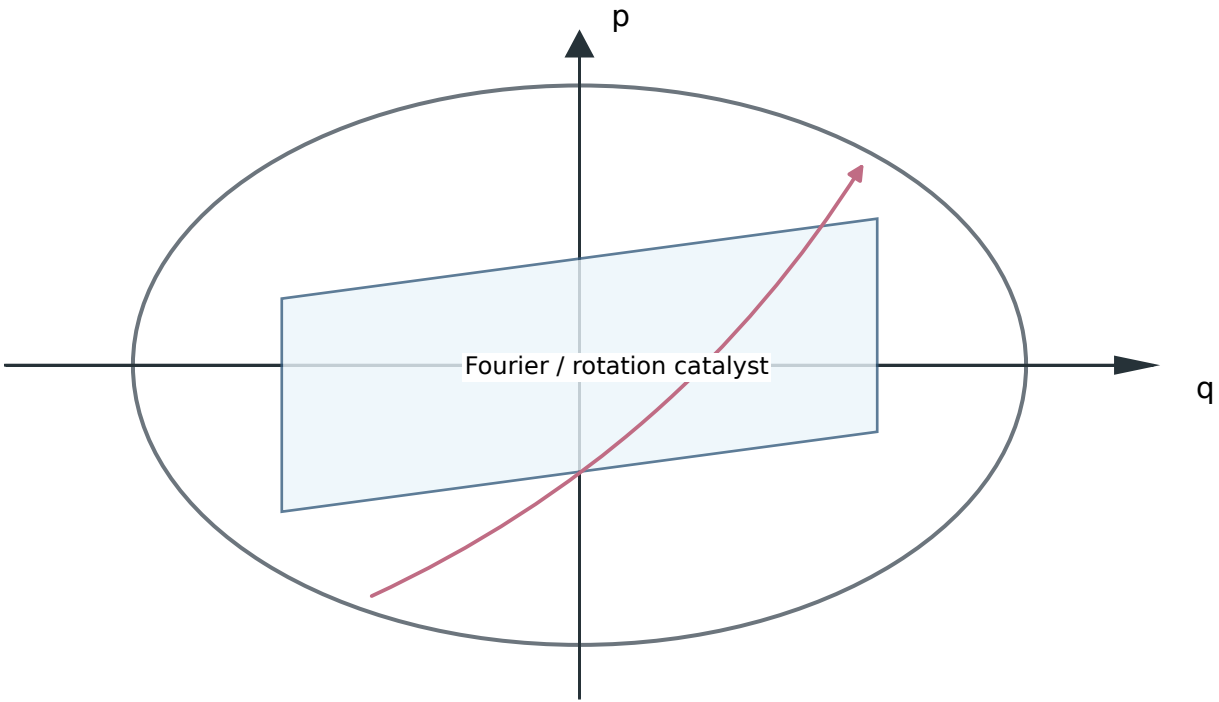
Gaussian analogue: shears, rotations, and temporary quadrature mixing



X_A = [[I,A],[0,I]], Z_B = [[I,0],[B,I]], F X_A F^{-1} = Z_{-A}